

$$\frac{1}{j} = \frac{1}{\sqrt{-1}} \cdot \frac{\sqrt{-1}}{\sqrt{-1}} = \frac{\sqrt{-1}}{-1} = -j$$

### Polar Form

$$c = r \cdot e^{j\theta} = r \angle \theta$$

### Conversion Between Rectangular and Polar

$$r = \sqrt{x^2 + y^2} \quad y = rsin(\theta)$$

$$\theta = \tan^{-1}(\frac{y}{x}) \quad x = rcos(\theta)$$

### Euler's Formula:

$$e^{j\theta} = \cos(\theta) + j \cdot \sin(\theta)$$

### Useful Identities:

$$e^{j90^\circ} = e^{j\frac{\pi}{2}} = j$$

$$e^{j\pi} = -1$$

$$\text{For } c = x + jy = re^{j\theta}$$

$$c_* = \text{complex conjugate of } c = x - jy = re^{-j\theta}$$

### Laplace transforms

$$\mathcal{L}\{\delta(t)\} = 1 \quad \mathcal{L}\{te^{\lambda t}u(t)\} = \frac{1}{(s-\lambda)^2}$$

$$\mathcal{L}\{u(t)\} = \frac{1}{s} \quad \mathcal{L}\{t^n e^{\lambda t}u(t)\} = \frac{n!}{(s-\lambda)^{n+1}}$$

$$\mathcal{L}\{tu(t)\} = \frac{1}{s^2} \quad \mathcal{L}\{x(t-t_0)\} = X(s)e^{-st_0}, t_0 \geq 0$$

$$\mathcal{L}\{t^n u(t)\} = \frac{1}{s^{n+1}} \quad \mathcal{L}\{\sin(bt)u(t)\} = \frac{b}{s^2+b^2}$$

$$\mathcal{L}\{e^{\lambda t}u(t)\} = \frac{1}{s-\lambda} \quad \mathcal{L}\{\cos(bt)u(t)\} = \frac{s}{s^2+b^2}$$

$$\mathcal{L}\{e^{-at}\cos(bt)u(t)\} = \frac{s+a}{(s+a)^2+b^2}$$

$$\mathcal{L}\{e^{-at}\sin(bt)u(t)\} = \frac{b}{(s+a)^2+b^2}$$

$$\mathcal{L}\{re^{-at}\cos(bt+\theta)u(t)\} = \frac{r \cos(\theta) + (a \cos(\theta) - br \sin(\theta))}{s^2 + 2as + (a^2 + b^2)}$$

$$= \frac{0.5re^{j\theta}}{s+a-jb} + \frac{-0.5re^{j\theta}}{s+a+jb}$$

$$= \frac{A+jB}{s^2+2as+c}$$

Where

$$r = \sqrt{\frac{A^2 + B^2 - 2ABa}{b^2}}$$

$$\theta = \tan^{-1}\left(\frac{A-a-B}{Ab}\right)$$

$$b = \sqrt{c = a^2}$$

$$\mathcal{L}\{e^{-at}[A\cos(bt) + \frac{B-Aa}{b}\sin(bt)]u(t)\} = \frac{As+B}{s^2+2as+c}$$

### Convolutions

$$x_1 * x_2 = \int_{-\infty}^{\infty} x_1(\tau) \cdot x_2(t-\tau) \cdot d\tau$$

$$yzs(t) = x(t) * h(t)$$

$$x(at), a \geq 0 \Leftrightarrow \frac{1}{a}X(\frac{s}{a})$$

$$x_1(t) * x_2(t) \Leftrightarrow X_1(s)X_2(s)$$

$$x_1(t)x_2(t) \Leftrightarrow 12\pi j X_1(s) * X_2(s)$$

$$x(0^+) \Leftrightarrow \lim_{s \rightarrow \infty} sX(s) (n > m)$$

$$x(\infty) \Leftrightarrow \lim_{s \rightarrow 0} sX(s) (\text{poles of } s \text{ in LHP})$$

### Fourier Transforms

$$X(\omega) = \mathcal{F}[x(t)] = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$x(t) = \mathcal{F}^{-1}[X(\omega)] = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

Sufficient Condition for FT Existence:

$$\int_{-\infty}^{\infty} |x(t)| dt$$

$$x(t) \quad X(\omega)$$

$$e^{-at}u(t) \quad \frac{1}{a+j\omega} \quad a > 0$$

$$e^{at}u(-t) \quad \frac{1}{a-j\omega} \quad a > 0$$

$$e^{-a|t|} \quad \frac{2a}{a^2 + \omega^2} \quad a > 0$$

$$te^{-at}u(t) \quad \frac{1}{(a+j\omega)^2} \quad a > 0$$

$$t^n e^{-at}u(t) \quad \frac{n!}{(a+j\omega)^{n+1}} \quad a > 0$$

$$\delta(t) \quad 1$$

$$1 \quad 2\pi\delta(\omega)$$

$$e^{j\omega t} \quad 2\pi\delta(\omega - \omega_0)$$

$$\cos \omega_0 t \quad \pi[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]$$

$$\sin \omega_0 t \quad j\pi[\delta(\omega - \omega_0) - \delta(\omega + \omega_0)]$$

$$u(t) \quad \pi\delta(\omega + \frac{1}{j\omega})$$

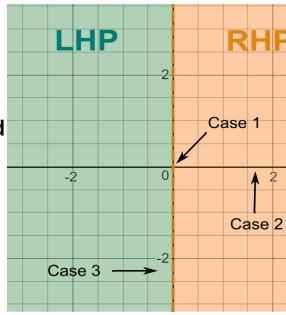
$$\text{sgn}t \quad \frac{2}{j\omega}$$

$$\cos \omega_0 t u(t) \quad \frac{\pi}{2}[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)] + \frac{j\omega_0}{\omega_0^2 - \omega^2}$$

$$\sin \omega_0 t u(t) \quad \frac{\pi}{2}[\delta(\omega - \omega_0) - \delta(\omega + \omega_0)] + \frac{\omega_0}{\omega_0^2 - \omega^2}$$

$$e^{-at} \sin \omega_0 t u(t) \quad \frac{\omega_0}{(a+j\omega)^2 + \omega_0^2} \quad a > 0$$

$$e^{-at} \cos \omega_0 t u(t) \quad \frac{a+j\omega}{(a+j\omega)^2 + \omega_0^2} \quad a > 0$$



### Classes of complex exponential functions

#### Case 1:

When  $s = 0, k \cdot e^{st} = k$  (a constant)

#### Case 2:

When  $\omega = 0, e^{st} = e^{\sigma t}$  (a monotonic exponential)  $e^{st} = e^{\sigma t}[\cos(\omega t) + j\sin(\omega t)]$

#### Case 3: When $\sigma = 0$ , (sinusoidal)

Case 4: No restriction, (exponentially varying sinusoid)

$$\operatorname{Re}[e^{st}] = e^{\sigma t}\cos(\omega t)$$

$$\operatorname{Im}[e^{st}] = e^{\sigma t}\sin(\omega t)$$

Single-Input-Single-Output (SISO) System.

$$x(t) \Rightarrow [\text{System}] \Rightarrow y(t)$$

Linearity - A system is linear if it obeys superposition:

$$\text{if } x_1 \Rightarrow y_1 \text{ and } x_2 \Rightarrow y_2$$

then

$$k_1x_1 + k_2x_2 \Rightarrow k_1y_1 + k_2y_2$$

where  $k_1$  and  $k_2$  are constants

Zero Input Response:  $x(t) = 0$

Zero State Response:  $x_0 = 0$

Laplace Transform Properties:

$$x_1(t) + x_2(t) \Leftrightarrow X_1(s) + X_2(s)$$

$$kx_1(t) \Leftrightarrow kX_1(s)$$

$$\frac{dx}{dt} \Leftrightarrow sX(s) - x(0^-)$$

$$\frac{d^2x}{dt^2} \Leftrightarrow sX(s) - x(0^-) - x'(0^-)$$

$$\frac{d^n x}{dt^n} \Leftrightarrow s^n X(s) - \sum_{k=1}^n s^{n-k} x^{k-1}(0^-)$$

$$\int_0^t x(\tau) d\tau \Leftrightarrow \frac{1}{s} X(s)$$

$$\int_{-\infty}^t x(t) d\tau \Leftrightarrow \frac{1}{s} X(s) + \frac{1}{s} \int_{-\infty}^0 x(t) dt$$

$$x(t)e^{-s_0 t} \Leftrightarrow X(s-s_0)$$

$$-tx(t) \Leftrightarrow dX(s)ds$$

Forms of Euler's Formula:

$$e^{jt} = \cos t + j\sin t$$

$$\sin t = \frac{e^{jt} - e^{-jt}}{2j}$$

$$\cos t = \frac{e^{jt} + e^{-jt}}{2}$$

$$\text{sinc} = \frac{\sin(t)}{t}$$

Delta Function Properties

$$\delta(t) = \frac{f(x)}{x(x+0)(x+b)^2(x^2+c^2)} = \frac{A}{x} + \frac{B}{x+0} + \frac{C}{x+b} + \frac{D}{(x+b)^2} + \frac{E}{x^2+c^2}$$

$$\text{a) } \delta(-t) = \delta(t)$$

$$\text{b) } \int_{-\infty}^{\infty} x(t)\delta(t-T) dt = x(T)\delta(t-T)$$

$$\int_{-\infty}^{\infty} x(t)\delta(t) dt = \int_{-\infty}^{\infty} x(0)\delta(t) dt$$

$$= x(0) \cdot 1$$

$$\text{Exponential F.S.:}$$

[Add definition of FS and exponential FS]

$$\omega_n = \frac{2\pi}{T_0}(n+1)$$

$$x(t) = \sum_{n=-\infty}^{\infty} D_n e^{jn\omega_0 t}$$

$$D_n = \frac{1}{T_0} \int_{T_0}^{\infty} x(t) \cdot e^{-jn\omega_0 t} dt$$

$$D_0 = \frac{1}{T_0} \int_{T_0}^{\infty} x(t) dt = a_0 = c_0$$

$$D_{-n} = D_n^* = \frac{a_n + jb_n}{2}$$

Amplitude Spectrum:  $|D_n|$  vs.  $n \cdot \omega_0$

Phase Spectrum:  $4D_n$  vs.  $n \cdot \omega_0$

$$|D_{-n}| = |D_n|$$

$$4D_{-n} = -4D_n$$

Steady State:

$$\text{for } x(t) = C_0 + \sum_{n=1}^{\infty} C_n \cdot \cos(n \cdot \omega_0 t + \theta_n)$$

$$y(t) = C_0 H(0) + \sum_{n=1}^{\infty} C_n \cdot H(jn\omega_0) \cos(n \cdot \omega_0 t + \theta_n + \Delta H(jn\omega_0))$$

Amplitude Spectrum:  $C_n \cdot |H(jn\omega_0)|$  vs.  $n \cdot \omega_0$

Phase Spectrum:  $\theta_n + \Delta H(jn\omega_0)$  vs.  $n \cdot \omega_0$

Given a BIBO system where the input is  $x(t) = A \cos(\omega_0 t + \phi)$  [As is the compact form of F.S.]

Note: improper fractions are ok for this situation.

$$y(t) = A|H(j\omega_0)| \cdot \cos(\omega_0 t + \phi + \Delta H(j\omega_0))$$

Where  $|H(j\omega_0)|$

= [replace all multiplied values as complex numbers in  $H(j\omega_0)$  with distance formulas]

$$= \left\{ (a + j\omega_0) \Rightarrow \sqrt{a^2 + \omega_0^2} \right\}$$

and

$$\Delta H(j\omega) = \tan^{-1}\left(\frac{\omega_0}{a}\right)$$

Inverse Hyperbolic Definitions

$$\operatorname{arcsinh}(z) = \ln(z + [\sqrt{z^2 + 1}])$$

$\operatorname{arccosh}(z) = \ln(z + [\sqrt{z^2 - 1}])$

Hyperbolic Trig Functions:

Definitions

$$\operatorname{sinh}(t) = \frac{e^t - e^{-t}}{2}$$

$$\operatorname{cosh}(t) = \frac{1}{\operatorname{sinh}(t)} = \frac{2}{e^t + e^{-t}}$$

$$\operatorname{sech}(t) = \frac{1}{\operatorname{cosh}(t)} = \frac{2}{e^t + e^{-t}}$$

$$\operatorname{tanh}(t) = \frac{\operatorname{sinh}(t)}{\operatorname{cosh}(t)} = \frac{e^t - e^{-t}}{e^t + e^{-t}}$$

Relations to Trigonometric Functions

$$\operatorname{sinh}(z) = -j \sin(iz)$$

$$\operatorname{cosh}(z) = i \csc(iz)$$

$$\operatorname{cosh}(z) = \cos(iz)$$

$$\operatorname{sech}(z) = \sec(iz)$$

$$\operatorname{tanh}(z) = -j \tan(iz)$$

$$\operatorname{coth}(z) = j \cot(iz)$$

$$\operatorname{cosec}(z) = \frac{1}{\operatorname{sinh}(z)}$$

$$\operatorname{cosec}(z) = \frac{1}{\operatorname{cosh}(z)}$$

$$\operatorname{cosec}(z) = \frac{1}{\operatorname{sech}(z)}$$

$$\operatorname{cosec}(z) = \frac{1}{\operatorname{tanh}(z)}$$

$$\operatorname{cosec}(z) = \frac{1}{\operatorname{coth}(z)}$$

$$\operatorname{cosec}(z) = \frac{1}{\operatorname{cosec}(z)}$$

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